

Unit and Constant Definition

$$\text{cycle} := 2 \cdot \pi \cdot \text{rad}$$

$$\text{Hz} := \frac{\text{cycle}}{\text{sec}}$$

$$\text{Air Density : } \rho := 1.164 \cdot \frac{\text{kg}}{\text{m}^3}$$

$$\text{Speed of Sound : } c := 345 \cdot \frac{\text{m}}{\text{sec}}$$

Set-up Counters

Frequency Domain

$$N := \frac{19995}{5}$$

$$s := 2, 3 \dots N$$

$$d\omega := 5 \cdot \text{Hz}$$

Import Driver Measured Data - On Axis

Data := 0 f := 0 Temp := 0

Data := READPRN("DX3_SYS1.FRD")

k_{max} := rows(Data) k := 0, 1 .. k_{max} - 1

f_k := Data_{k,0}

Temp_k := Data_{k,1}

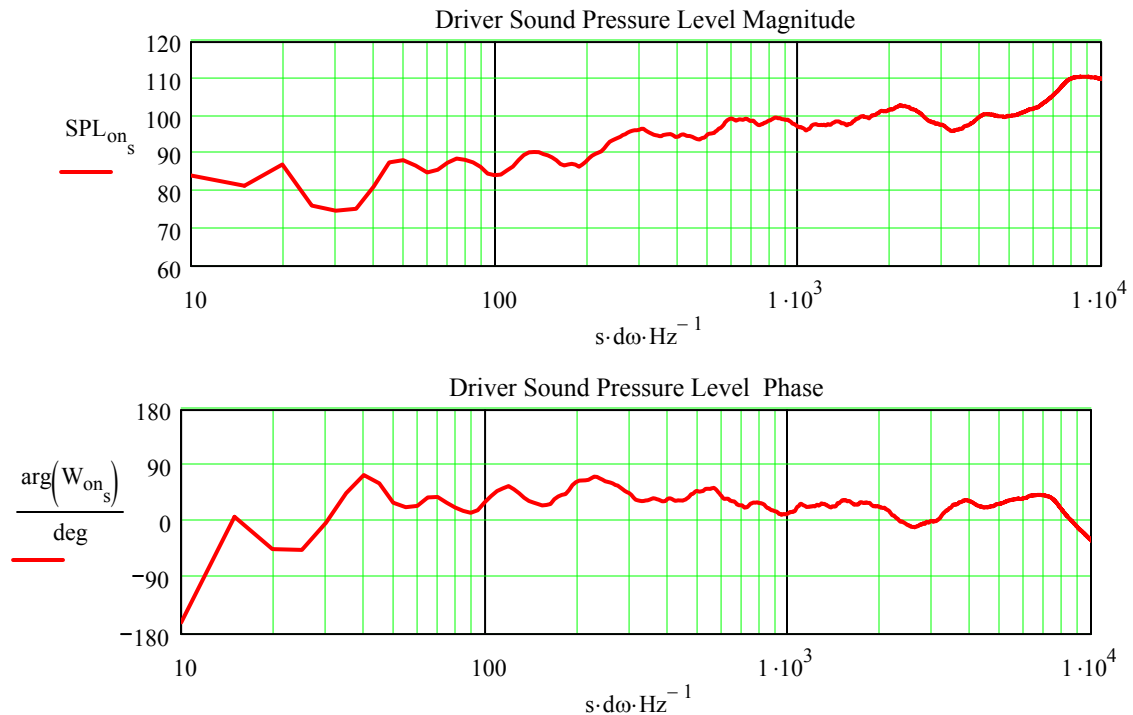
smooth := cspline(f, Temp) Mag(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) M_s := $2 \cdot 10^{-5} \cdot 10^{\frac{\text{Mag}(s)}{20}}$

Temp_k := Data_{k,2}

smooth := cspline(f, Temp) Phase(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) P_s := Phase(s)

W_{on_s} := (M_s · Pa) · exp(j · P_s · deg)

SPL_{on_s} := $20 \cdot \log\left(\frac{|W_{on_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}}\right)$



Import Driver Measured Data - Off Axis

Data := 0 f := 0 Temp := 0

Data := READPRN("DX3_OFF1.FRD")

k_{max} := rows(Data) k := 0, 1 .. k_{max} - 1

f_k := Data_{k,0}

Temp_k := Data_{k,1}

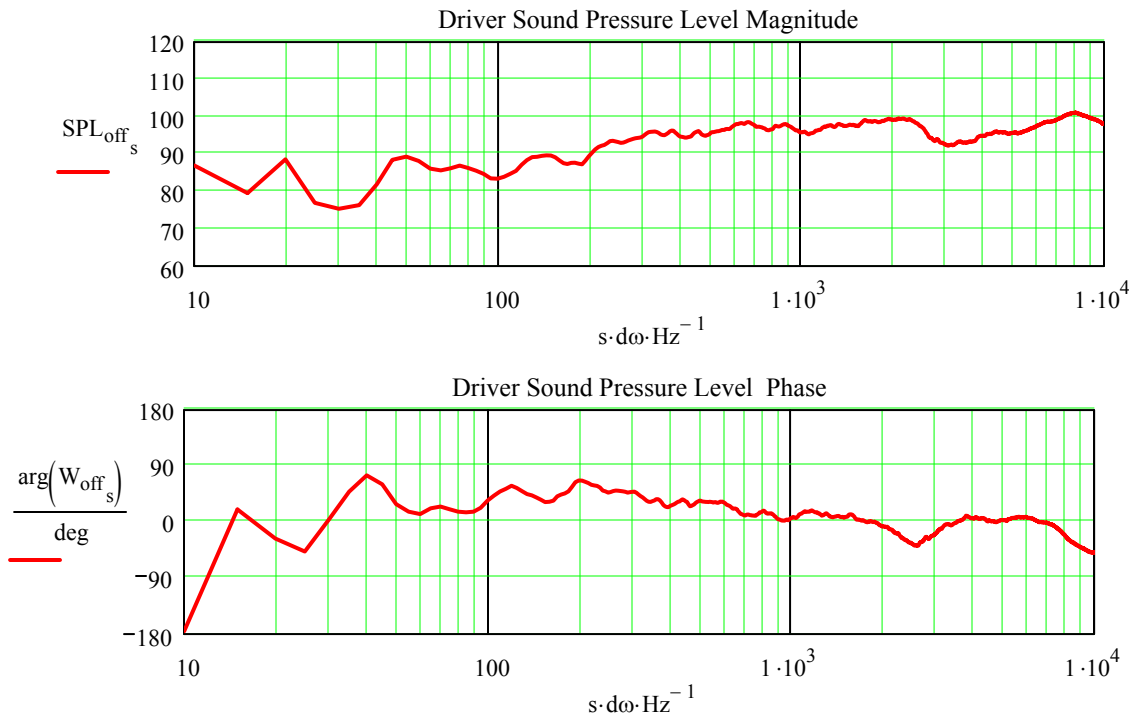
smooth := cspline(f, Temp) Mag(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) M_s := $2 \cdot 10^{-5} \cdot 10^{\frac{\text{Mag}(s)}{20}}$

Temp_k := Data_{k,2}

smooth := cspline(f, Temp) Phase(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) P_s := Phase(s)

W_{off_s} := (M_s · Pa) · exp(j · P_s · deg)

SPL_{off_s} := $20 \cdot \log\left(\frac{|W_{\text{off}_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}}\right)$



Import Woofer Impedance Data

Data := 0 f := 0 Temp := 0

Data := READPRN("DX3_IMP1.ZMA")

k_{max} := rows(Data) k := 0, 1 .. k_{max} - 1

f_k := Data_{k,0}

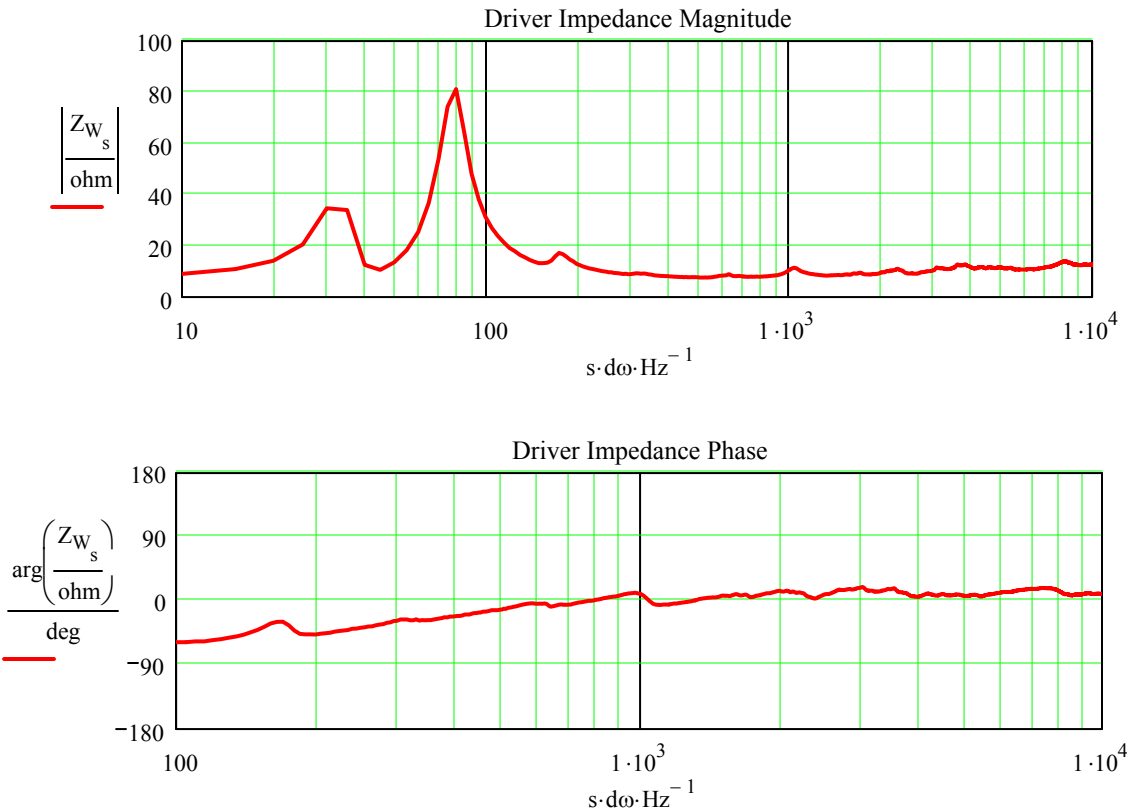
Temp_k := Data_{k,1}

smooth := cspline(f, Temp) Mag(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) M_s := Mag(s)

Temp_k := Data_{k,2}

smooth := cspline(f, Temp) Phase(s) := interp(smooth, f, Temp, $\frac{s \cdot d\omega}{\text{Hz}}$) P_s := Phase(s)

Z_{W_s} := [(M_s · ohm) · exp(j · P_s · deg)]



Compensation Circuit

$$R_e := 7.1 \cdot \text{ohm}$$

$$1.25 \cdot R_e = 8.875 \text{ ohm}$$

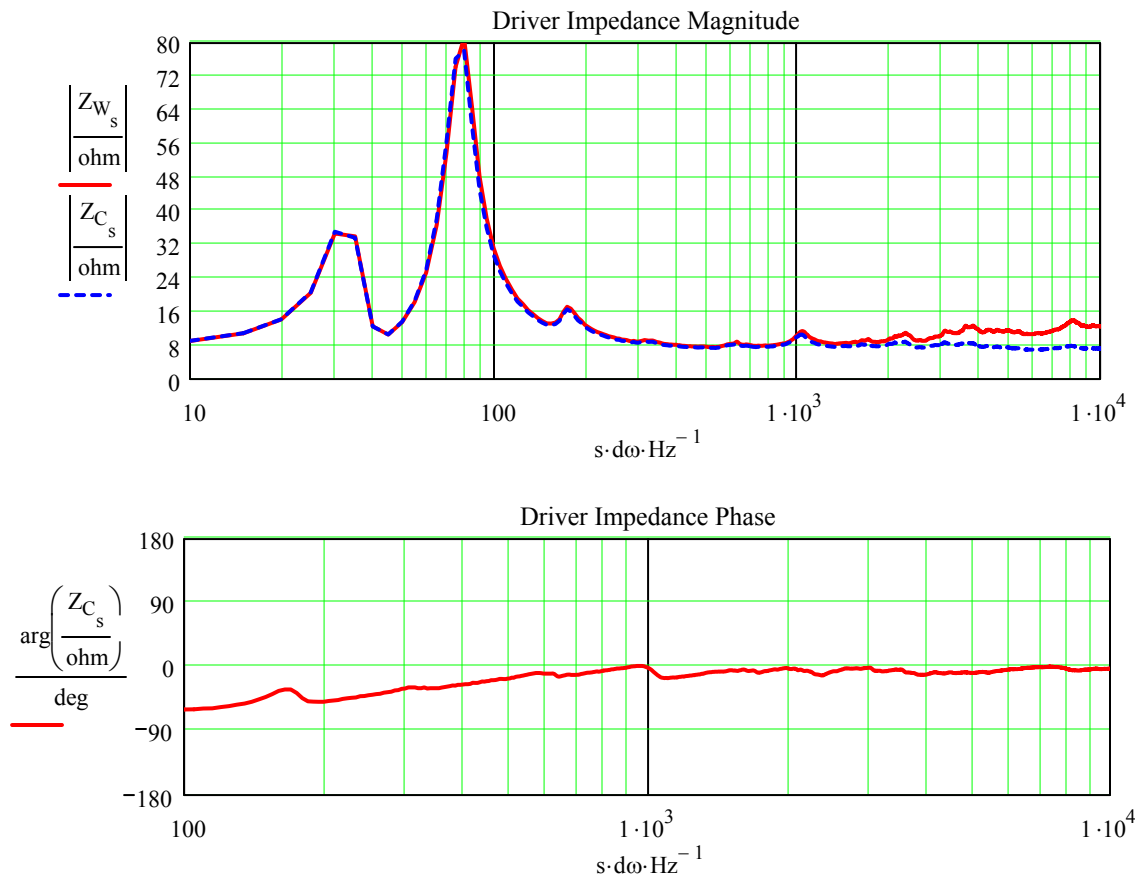
$$L_{VC} := 0.4 \cdot \text{mH}$$

$$L_{VC} \cdot (1.25 \cdot R_e)^{-2} = 5.078 \mu\text{F}$$

$$R_c := 15 \cdot \text{ohm} \quad (\text{Mills } 15 \text{ ohm} / 12 \text{ watt resistor, Parts Express \# } 005-15)$$

$$C_c := 3.2 \cdot \mu\text{F} \quad (\text{Solen } 3 \text{ uF, Parts Express \# } 027-542)$$

$$Z_{C_s} := \left[\left(Z_{W_s} \right)^{-1} + \left(R_c + \frac{1}{j \cdot s \cdot d\omega \cdot C_c} \right)^{-1} \right]^{-1}$$



Baffle Step Correction Circuit Design

$R_1 := 8 \cdot \text{ohm}$ (Mills 8 ohm / 12 watt resistor, Parts Express # 005-8)

$R_2 := 15 \cdot \text{ohm}$ (Mills 15 ohm / 12 watt resistor, Parts Express # 005-15)

$L_1 := 4.0 \cdot \text{mH}$ (ERSE Super Q 4.0 mH, Parts Express # 266-922)

$L_2 := 4.0 \cdot \text{mH}$ (ERSE Super Q 4.0 mH, Parts Express # 266-922)

$$Z_{1_s} := \left[R_1^{-1} + (0.385 \cdot \text{ohm} + j \cdot s \cdot d\omega \cdot L_1)^{-1} \right]^{-1}$$

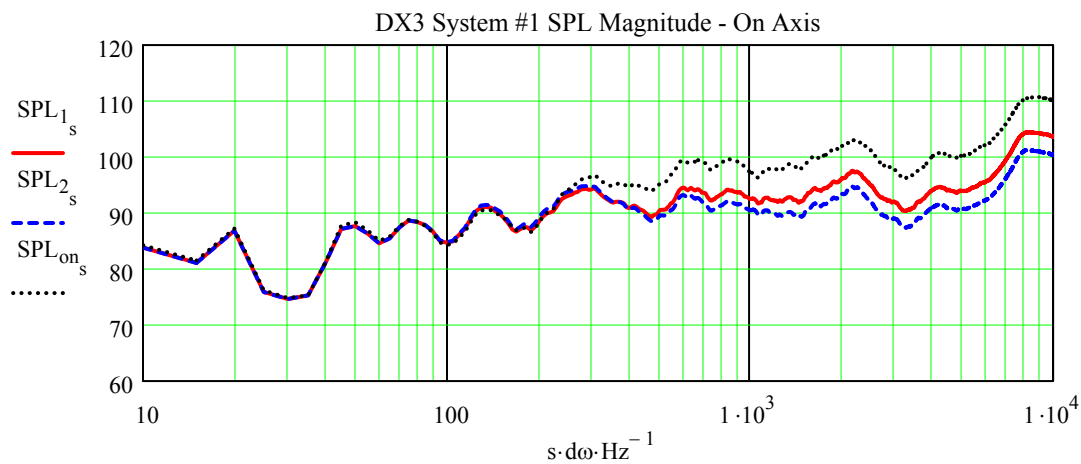
$$Z_{2_s} := \left[R_2^{-1} + (0.385 \cdot \text{ohm} + j \cdot s \cdot d\omega \cdot L_2)^{-1} \right]^{-1}$$

$$V_{1_s} := Z_{C_s} \cdot (Z_{1_s} + Z_{C_s})^{-1}$$

$$V_{2_s} := Z_{C_s} \cdot (Z_{2_s} + Z_{C_s})^{-1}$$

$$\text{SPL}_{1_s} := 20 \cdot \log \left(\frac{|V_{1_s} \cdot W_{\text{on}_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}} \right)$$

$$\text{SPL}_{2_s} := 20 \cdot \log \left(\frac{|V_{2_s} \cdot W_{\text{on}_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}} \right)$$



$$\text{SPL}_{1_s} := 20 \cdot \log \left(\frac{|V_{1_s} \cdot W_{\text{off}_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}} \right)$$

$$\text{SPL}_{2_s} := 20 \cdot \log \left(\frac{|V_{2_s} \cdot W_{\text{off}_s}|}{2 \cdot 10^{-5} \cdot \text{Pa}} \right)$$

